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Nonlinear Optimization Spring Semester 2024

EXERCISE 10

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Homework Problem 10.1 (Comparing the Strength of CQs) 6 Points

Definition 6.6 LICQ MFCQ ACQ GCQ (6.15)

Show that generally



by investigating the fol

$$\begin{array}{ll} \text{Minimize} & f(x) & \text{where } x \in \mathbb{R}^2 \\ \text{subject to} & x_1 \leq 0 \\ & x_2 \leq 0 \\ & x_1 x_2 = 0 \end{array} \right\}$$
(P1)

$$\begin{array}{ll} \text{Minimize} & f(x) & \text{where } x \in \mathbb{R}^2 \\ \text{subject to} & q(x_1) - x_2 \le 0 \\ & q(x_1) + x_2 \le 0 \end{array} \end{array} \right\} \quad \text{for} \quad q(x_1) \coloneqq \begin{cases} (x_1 + 1)^2, & x_1 < -1, \\ 0, & -1 \le x_1 \le 1, \\ (x_1 - 1)^2, & x_1 > 1, \end{cases} \quad (P2)$$

$$\begin{array}{ll} \text{Minimize} & f(x) & \text{where } x \in \mathbb{R}^2 \\ \text{subject to} & -x_1^3 - x_2 \le 0 \\ & -x_2 \le 0 \end{array} \right\}$$
(P3)

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From the lecture notes, we know that Lemma 6.17 Corollary 6.14

llowing problems P1 to P3 at
$$x^* = (0, 0)^T$$
:

$$\begin{array}{ll} \text{Minimize} & f(x) & \text{where } x \in \mathbb{R}^2 \\ \text{subject to} & x_1 \leq 0 \\ & x_2 \leq 0 \\ & x_1 x_2 = 0 \end{array} \right\}$$

Minimize
$$f(x)$$
 where $x \in \mathbb{R}^2$
subject to $-x^3 - x_2 \le 0$

Homework Problem 10.2 (Finding Solutions using First and Second Order Information) 6 Points Consider the problem

> Maximize $-(x_1-2)^2 - 2(x_2-1)^2$ where $x \in \mathbb{R}^2$ subject to $x_1 + 4x_2 \le 3$ and $x_1 \ge x_2$

Determine, which admissible points satisfy a constraint qualification (ACQ/GCQ/MFCQ/LICQ) and use first and second order information to compute all stationary points and solve the problem, i. e., find all optima and explain why they are local and/or global solutions.

Homework Problem 10.3 (Solvability and global solutions of equality constrained QPs) 6 Points Prove Lemma 9.2 of the lecture notes, i. e., the following statements for the quadratic problem

Minimize
$$\mathcal{L}(\overline{x},\overline{\lambda}) + \mathcal{L}_x(\overline{x},\overline{\lambda}) d + \frac{1}{2} d^{\mathsf{T}} \mathcal{L}_{xx}(\overline{x},\overline{\lambda}) d$$
, where $d \in \mathbb{R}^n$
subject to $h(\overline{x}) + h'(\overline{x}) d = 0$. (9.1)

- (*i*) Suppose that the linear system $h(\overline{x}) + h'(\overline{x}) d = 0$ is solvable, and that d_{part} is some particular solution. Suppose, moreover, that the reduced Hessian $Z^{\mathsf{T}} \mathcal{L}_{xx}(\overline{x}, \overline{\lambda}) Z$ is positive semidefinite. Then the objective in the reduced QP (9.3) is convex. In this case, the following are equivalent:
 - (a) The QP (9.1) possesses at least one (global) minimizer.
 - (b) The QP (9.1) is neither unbounded nor infeasible.
 - (c) The KKT conditions (9.2) are solvable.
 - (d) The reduced QP (9.3) possesses at least one (global) minimizer.
 - (e) The reduced QP (9.3) is not unbounded.
 - (f) The first-order optimality condition (9.4) is solvable.

The global minimizers of (9.1) are precisely the KKT points, i. e., the *d*-components of solutions (d, λ) to the KKT system (9.2).

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- (*ii*) Suppose that the linear system $h(\overline{x}) + h'(\overline{x}) d = 0$ is solvable, and that d_{part} is some particular solution. Suppose now that the reduced Hessian $Z^{\mathsf{T}} \mathcal{L}_{xx}(\overline{x}, \overline{\lambda}) Z$ is not positive semidefinite. Then the QP (9.1) and the reduced QP (9.3) are unbounded.
- (*iii*) Suppose that the linear system $h(\overline{x}) + h'(\overline{x}) d = 0$ is not solvable. Then the QP (9.1) is infeasible and the reduced QP cannot be formulated for lack of a particular solution d_{part} .

Homework Problem 10.4 (LICQ is equivalent to a unique Lagrange multiplier for certain QPs) 3 Points

Consider the (affine linearly) equality constrained quadratic optimization problem of the form

Minimize
$$\frac{1}{2}x^{\mathsf{T}}Ax + b^{\mathsf{T}}x + c$$
, where $x \in \mathbb{R}^n$
subject to $Cx = d$ (0.1)

for symmetric $A \in \mathbb{R}^{n \times n}$, $b \in \mathbb{R}^n$, $c \in \mathbb{R}$ and $C \in \mathbb{R}^{n \times n_{eq}}$, $d \in \mathbb{R}^{n_{eq}}$ and let x^* be a KKT-point of (0.1).

Show that the set $\Lambda(x^*)$ of Lagrange multipliers corresponding to x^* is a singleton if and only if the LICQ is satisfied at x^* .

Note: This proves the second set of equivalences in Equation (9.5).

Please submit your solutions as a single pdf and an archive of programs via moodle.

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