R. Herzog, G. Müller, E. Herberg, M. Hashemi Heidelberg University Nonlinear Optimization Spring Semester 2023

Exercise 10

Date issued: 19th June 2023 Date due: 27th June 2023

Homework Problem 10.1 (Solvability and global solutions of equality constrained QPs) 6 Points Prove Lemma 11.2 of the lecture notes, i. e., the following statements for the quadratic problem

Minimize
$$\mathcal{L}(\overline{x},\overline{\lambda}) + \mathcal{L}_x(\overline{x},\overline{\lambda}) d + \frac{1}{2} d^{\mathsf{T}} \mathcal{L}_{xx}(\overline{x},\overline{\lambda}) d$$
, where $d \in \mathbb{R}^n$
subject to $h(\overline{x}) + h'(\overline{x}) d = 0$. (11.1)

- (*i*) Suppose that the linear system $h(\overline{x}) + h'(\overline{x}) d = 0$ is solvable, and that d_{part} is some particular solution. Suppose, moreover, that the reduced Hessian $Z^{\mathsf{T}} \mathcal{L}_{xx}(\overline{x}, \overline{\lambda}) Z$ is positive semidefinite. Then the objective in the reduced QP (11.3) is convex. In this case, the following are equivalent:
 - (a) The QP (11.1) possesses at least one (global) minimizer.
 - (b) The QP (11.1) is neither unbounded nor infeasible.
 - (c) The KKT conditions (11.2) are solvable.
 - (d) The reduced QP (11.3) possesses at least one (global) minimizer.
 - (e) The reduced QP (11.3) is not unbounded.
 - (f) The first-order optimality condition (11.4) is solvable.

The global minimizers of (11.1) are precisely the KKT points, i. e., the *d*-components of solutions (d, λ) to the KKT system (11.2).

- (*ii*) Suppose that the linear system $h(\overline{x}) + h'(\overline{x}) d = 0$ is solvable, and that d_{part} is some particular solution. Suppose now that the reduced Hessian $Z^{\mathsf{T}} \mathcal{L}_{xx}(\overline{x}, \overline{\lambda}) Z$ is not positive semidefinite. Then the QP (11.1) and the reduced QP (11.3) are unbounded.
- (*iii*) Suppose that the linear system $h(\overline{x}) + h'(\overline{x}) d = 0$ is not solvable. Then the QP (11.1) is infeasible and the reduced QP cannot be formulated for lack of a particular solution d_{part} .

Homework Problem 10.2 (LICQ is equivalent to a unique Lagrange multiplier for certain QPs) 3 Points

Consider the (affine linearly) equality constrained quadratic optimization problem of the form

Minimize
$$\frac{1}{2}x^{\mathsf{T}}Ax + b^{\mathsf{T}}x + c$$
, where $x \in \mathbb{R}^n$
subject to $Cx = d$ (0.1)

for symmetric $A \in \mathbb{R}^{n \times n}$, $b \in \mathbb{R}^n$, $c \in \mathbb{R}$ and $C \in \mathbb{R}^{n \times n_{eq}}$, $d \in \mathbb{R}^{n_{eq}}$ and let x^* be a KKT-point of (0.1).

Show that the set $\Lambda(x^*)$ of Lagrange multipliers corresponding to x^* is a singleton if and only if the LICQ is satisfied at x^* .

Note: This proves the second set of equivalences in Equation (11.5).

Homework Problem 10.3 (Complementarity is equivalent to variational inequality) 3 Points Prove Lemma 11.4 of the lecture notes, i. e. the equivalence of the KKT complementarity condition

$$\mu \ge 0, \quad g(x) \le 0, \quad \mu^{\mathsf{T}} g(x) = 0$$
 (11.11b)

and the variational inequality

$$\mu \in K$$
 and $g(x)^{\mathsf{T}}(\nu - \mu) \le 0$ for all $\nu \in K$ (11.12)

with the closed convex cone $K \coloneqq \mathbb{R}_{\geq 0}^{n_{\text{ineq}}}$ (the non-negative orthant).

Homework Problem 10.4 (On the normal cone)

Prove Lemma 11.6 of the lecture notes, i. e., the following statements for a set $M \subseteq \mathbb{R}^n$ and $x \in M$:

(*i*) The normal cone is a closed convex cone.

3 Points

(*ii*) $N_M(x) = (M - \{x\})^\circ$ holds.

Additionally, prove that

(*iii*)
$$\mathcal{N}_M(x) \subseteq \mathcal{T}_M(x)^\circ$$
 but generally $\mathcal{N}_M(x) \neq \mathcal{T}_M(x)^\circ$.

Please submit your solutions as a single pdf and an archive of programs via moodle.

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